SHARED DATA STRUCTURES IN NESTED DATA PARALLELISM

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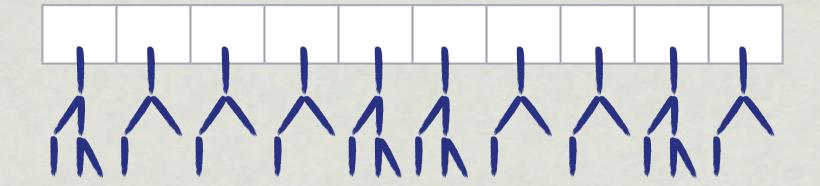
JOINT WORK WITH Gabriele Keller Roman Leshchinskiy Ben Lippmeier Simon Peyton Jones

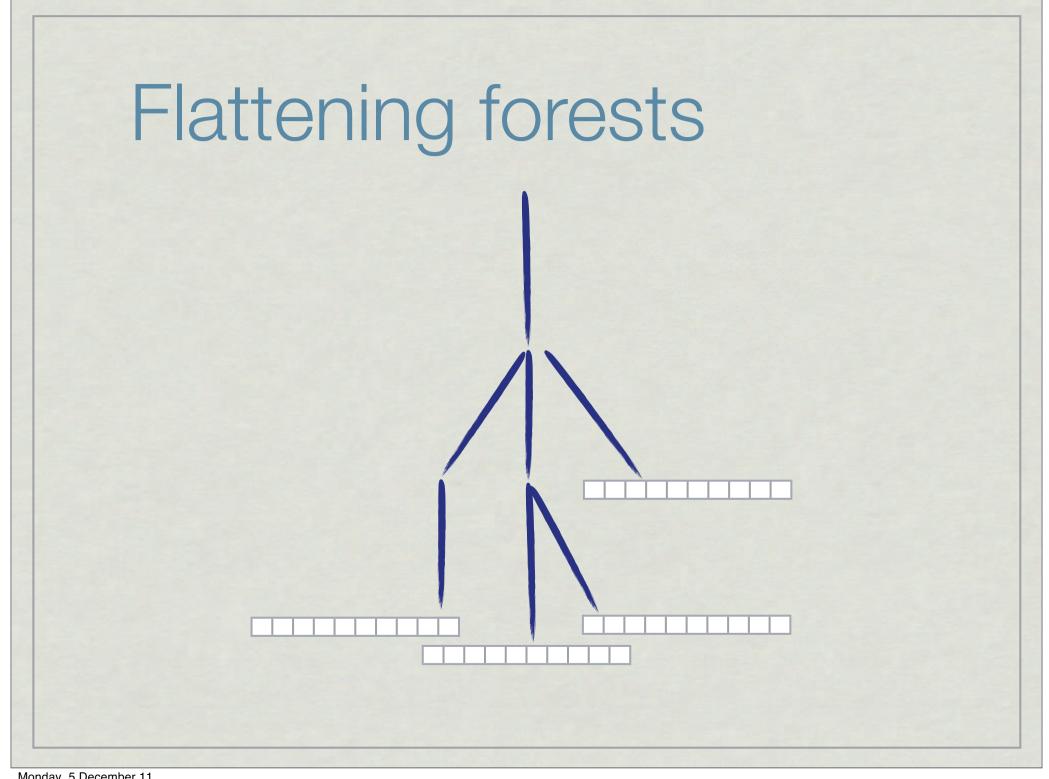


- * Flattening is a program transformation
- * It transforms both code and data structures
- * Scalar computations become array-valued
- * We perform it on GHC's Core language (an extended lambda calculus)

Part of the implementation of Data Parallel Haskell

Flattening forests





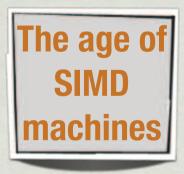
```
((x1,y1),(x2,y2)) = line;
n (x1-xo)*(y2-yo) - (y1-yo)*(x2-xo);

function hsplit(points,(p1,p2)) =
et cross = {cross_product(p,(p1,p2)): p in points};
  packed = {p in points; c in cross | plusp(c)};
n if (#packed < 2) then [p1] ++ packed
  else
    let pm = points[max_index(cross)];
    in flatten({hsplit(packed,ends): ends in [(p1,pm),(pm,p2)]});

function quick_hull(points) =
et x = {x : (x,y) in points};
  minx = points[min_index(x)];</pre>
```

* Introduced by Blelloch & Sabot for NESL







```
= (x1-xo) * (y2 - yo) - (y1 - yo) * (x2 - xo)

split :: [:Point:] -> Line -> [:Point:]
split points line@(p1, p2)
l lengthP packed Int.== 0 = [:p1:]
l otherwise
= concatP [: hsplit packed ends | ends <- [:(p1, pm), (pm, p2):] :)
where
    cross = [: distance p line | p <- points :]
    packed = [: p | (p,c) <- zipP points cross, c > 0.0 :]
    pm = points !: maxIndexP cross

uickHull :: [:Point:] -> [:Point:]
uickHull points
l lengthP points Int.== 0 = points
l otherwise
```

* We extended it to cover

sum types

data Either a b = Left a | Right b

recursive data types

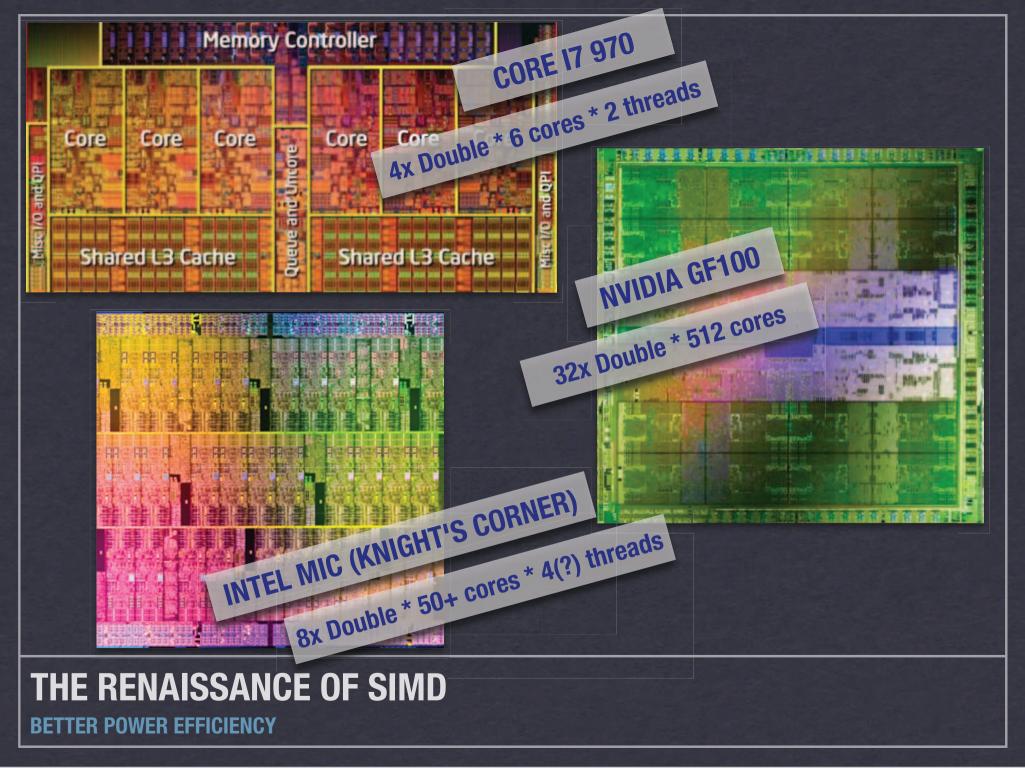
data Tree a = Tree a [:Tree a:]

higher-order functions

mapP :: (a -> b) -> [:a:] -> [:b:]

Flattening has a dual purpose

- * Produce SIMD-friendly code
- * Flatten nested data parallelism



Nested data parallelism

- * Enables sparse structures & irregular parallelism
- * Flat data parallelism is not modular!

[: myLibraryFun x | x <- xs :]

Is this function itself parallel?

With flat parallelism it cannot be parallel!



```
f :: Float -> Float -> Float
f x y z = x * y + z
```

The **lifted** version of f

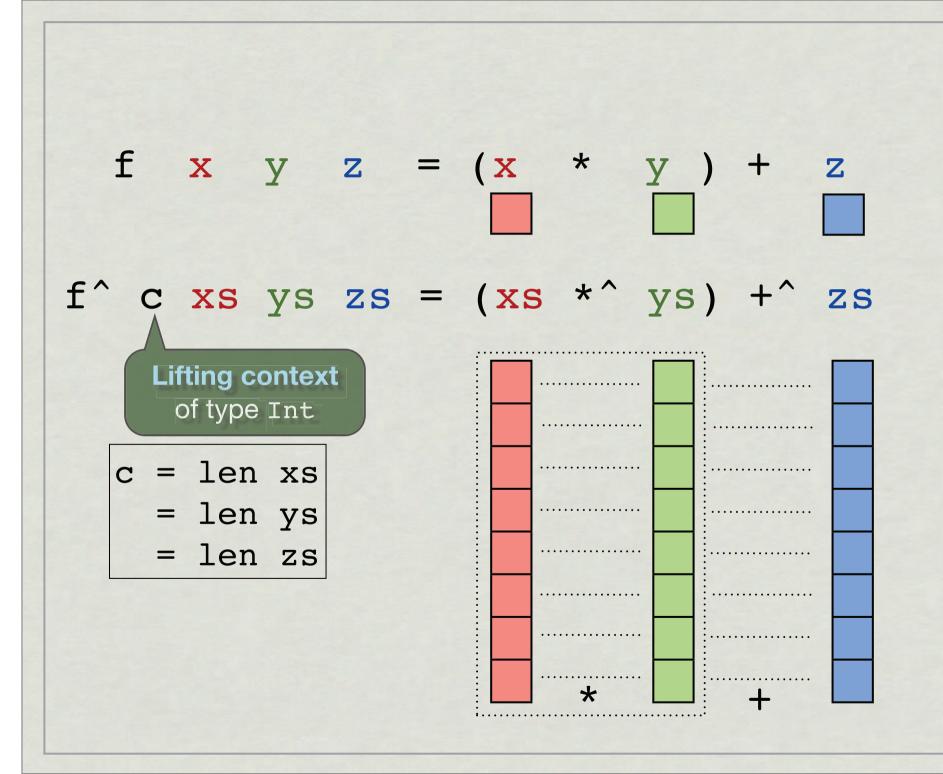


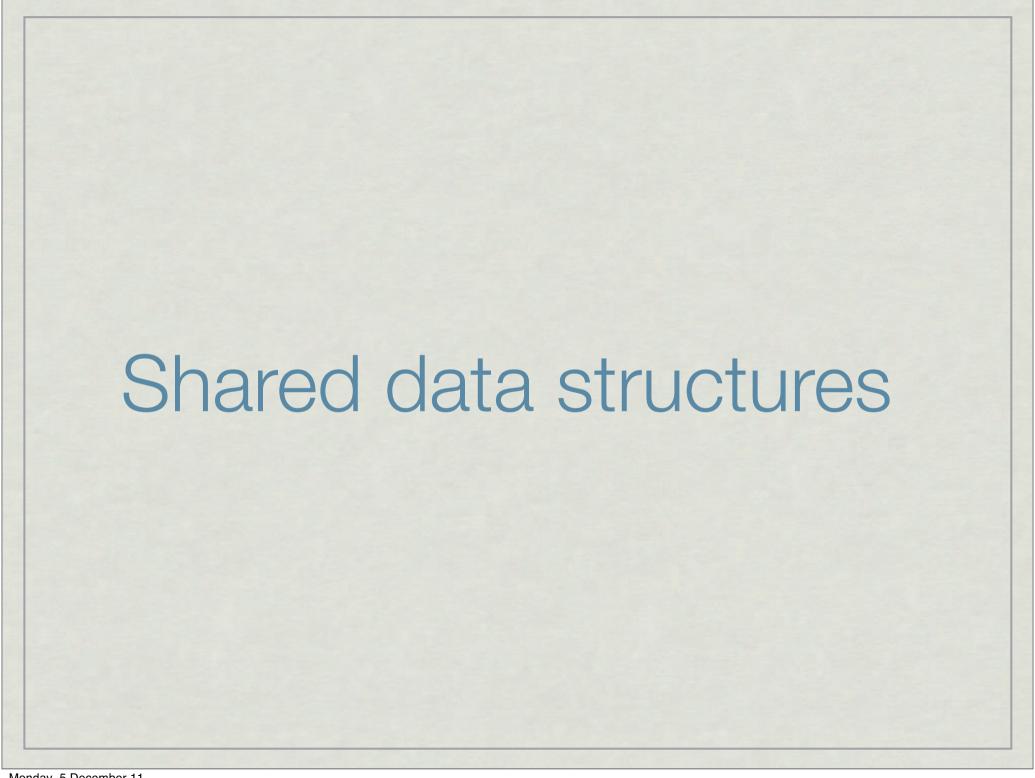
```
f^ :: [:Float:] -> [:Float:] -> [:Float:]
f^ xs ys zs = xs *^ ys +^ zs
```

We call flattening also vectorisation



f^ xs ys zs



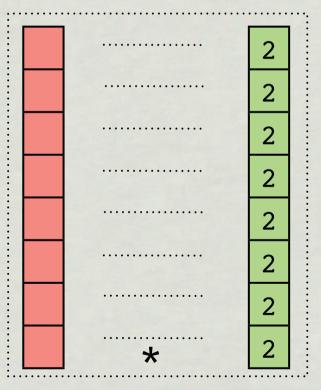


Constants shared across multiple parallel computations

$$f x = (\underline{x} * \underline{2}) + \underline{1}$$

rep = replicateP

$$f^c xs = (xs *^r rep c 2) +^r rep c 1$$



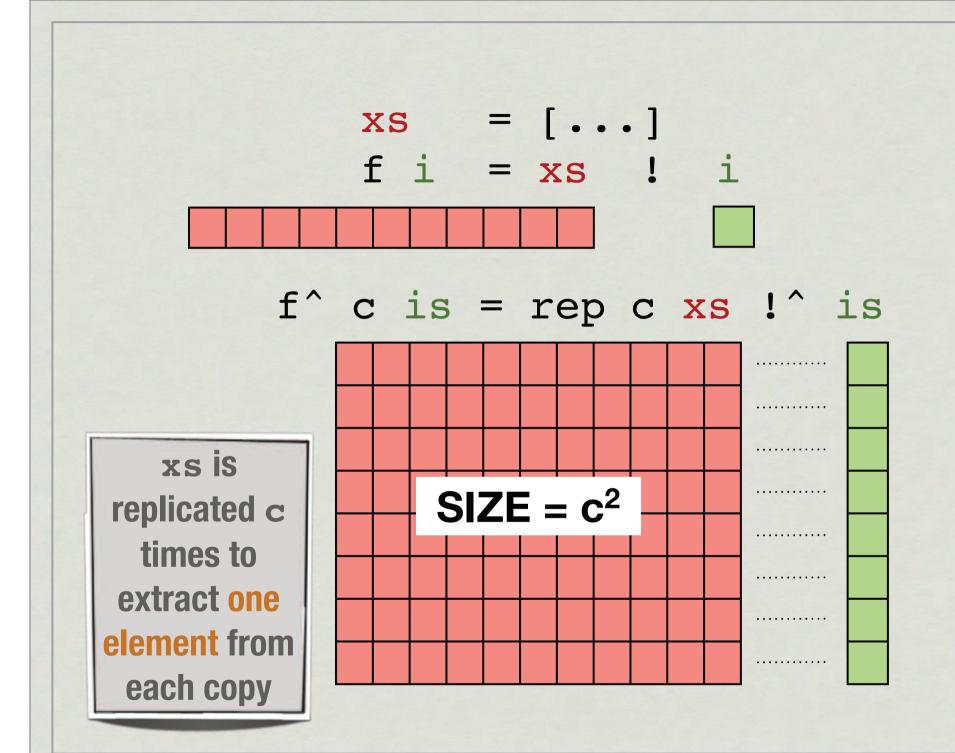
	1
	1
	1
	1
	1
	1
	1
+	1

* We need to replicate constants to respect the interface of (+^) and (*^)

* The same holds for user-defined lifted functions

* Vectorisation of partial application also leads to replication

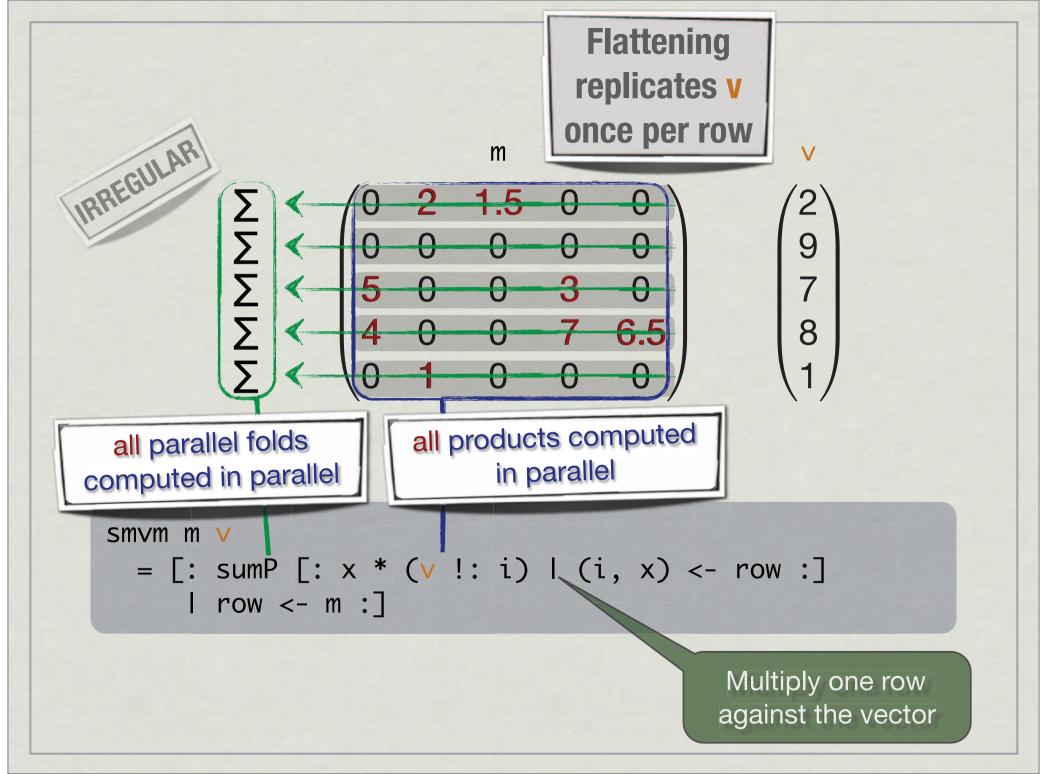
But this quickly leads to overheads!



Sparse-matrix vector multiplication

- * Realistic example program
- * Suffers from sharing the multiplied vector
- * Vector is replicated *n* times (for an *n*x*n* matrix)

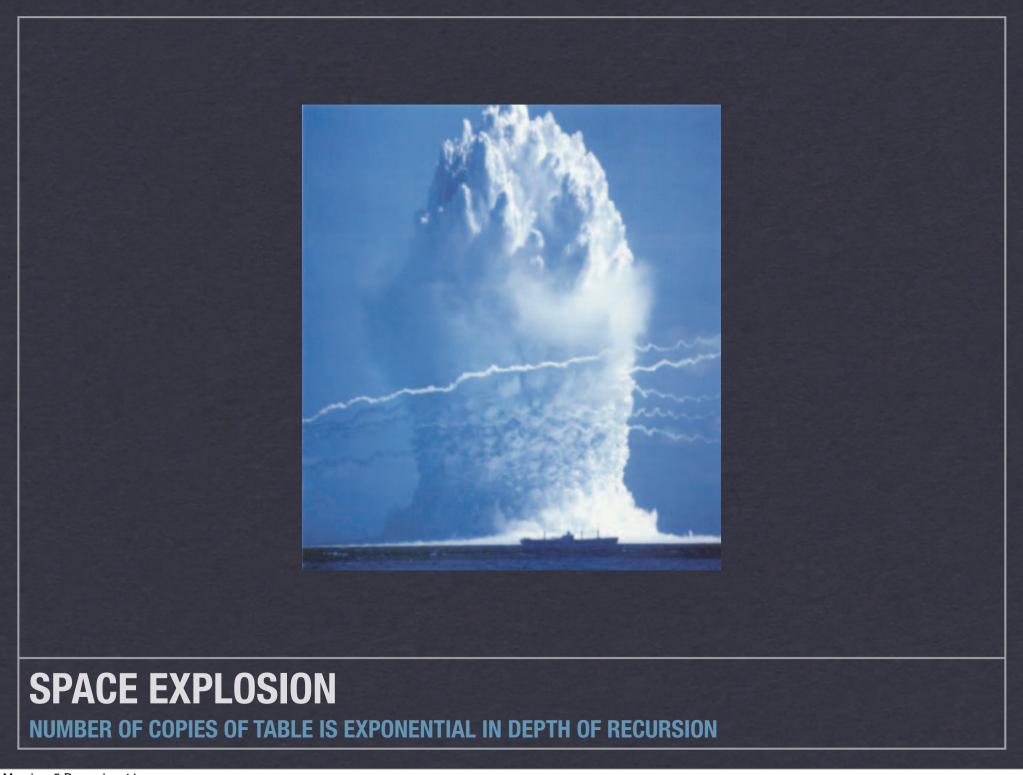
RANDOM SPARSE MATRIX index 1.5 sparse vector [:[:(1, 2), (2, 1.5):]sparse row (CSR) ,[::],[:(0, 5):],[:(0, 4), (3, 7), (4, 6.5):],[:(1, 1):]



A pathological example

Assume length is a power of 2

Shared use in two parallel invocations



This problem has been known for a while

- * Palmer, Prins & Westfold: Work-Efficient Nested Data-Parallelism
- * Blelloch & Greiner: A Provable Time and Space Efficient Implementation of NESL
- * Spoonhower, Blelloch, Harper & Gibbons: Space Profiling for Parallel Functional Programs

The issue is work as well as space efficiency!

First-order programs

- * Palmer et al. modified the flattening transformation
- * That modification doesn't extend to the higherorder case
- * It also only deals with the replicate function, but omits the other issues we will identify

Thread-based approaches

- * Blelloch & Greiner introduced a thread-based approach later extended by Spoonhower et al.
- * Instead of flattening, they use very fine-grained threads
- * In that setting, the crucial insight is to use the right scheduling policy (work stealing)

Consumers of replicate

```
f :: Int -> [:Float:]
f i = if p i then a!i else [::]
```

```
a :: [:[:Float:]:]
```



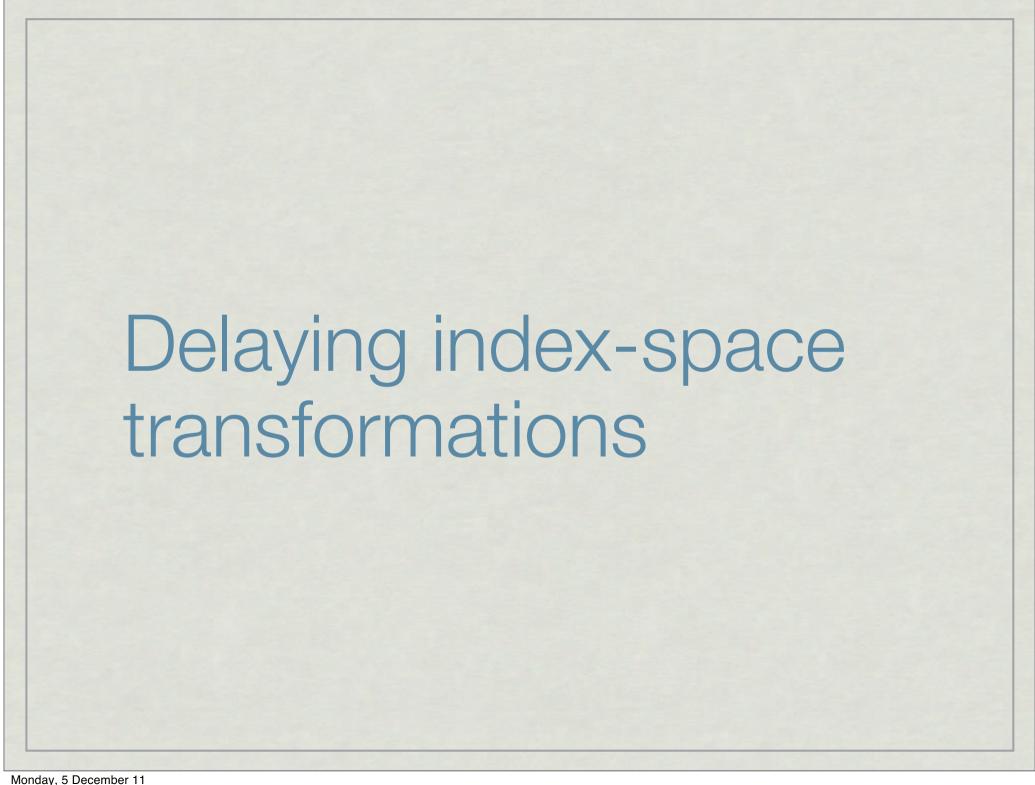
Expensive consumer

Our goal

- * Stick with flattening to support SIMD hardware
- * Avoid the space explosion
- * Avoid work inefficiency

we leave this to future work

* Prove that our implementation is time and space efficient



Index-space transformations

- * Operations that merely re-arrange array data
- * In particular those re-arranging subarrays of nested arrays

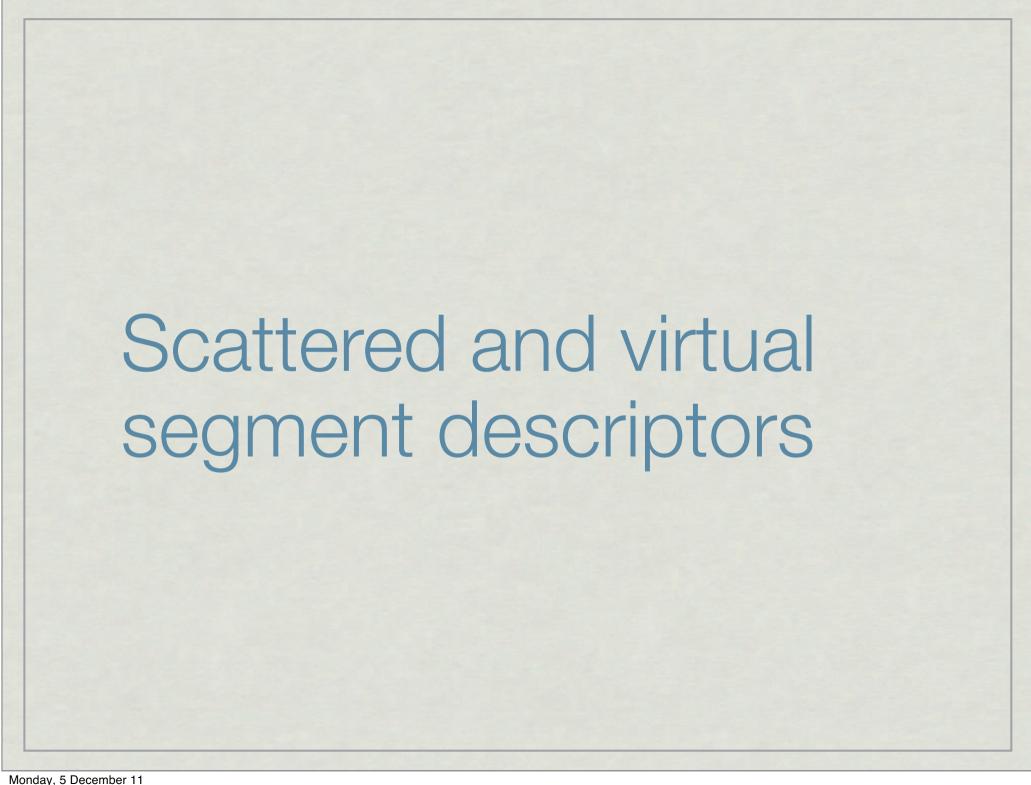
These get used in lifted array-processing functions

* replicate (segmented)
* index & slice (segmented)
* split & combine (segmented)
* append (segmented)
* back permutation

Our approach

- * Delay index-space transformations
- * Don't re-arrange subarrays eagerly
- * Instead, keep track of pending re-arrangement

The flattening transformation stays the same!



Library implements arrays generically using a data family

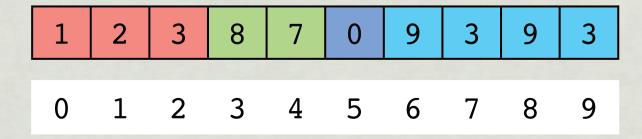
```
data Array (Array a) = Nested Segd (Array a)
data Segd = Segd (Array Int) (Array Int)
```

```
xs = Array (Array Int)
xs = [[1 2 3] [8 7] [0] [9 3 9 1]]
```

seg lens: [3 2 1 4]

seg starts: [0 3 5 6]

flat data:



Library implements arrays generically using a data family

```
data Array (Array a) = Nested Segd (Array a)
data Segd = Segd (Array Int) (Array Int)
```

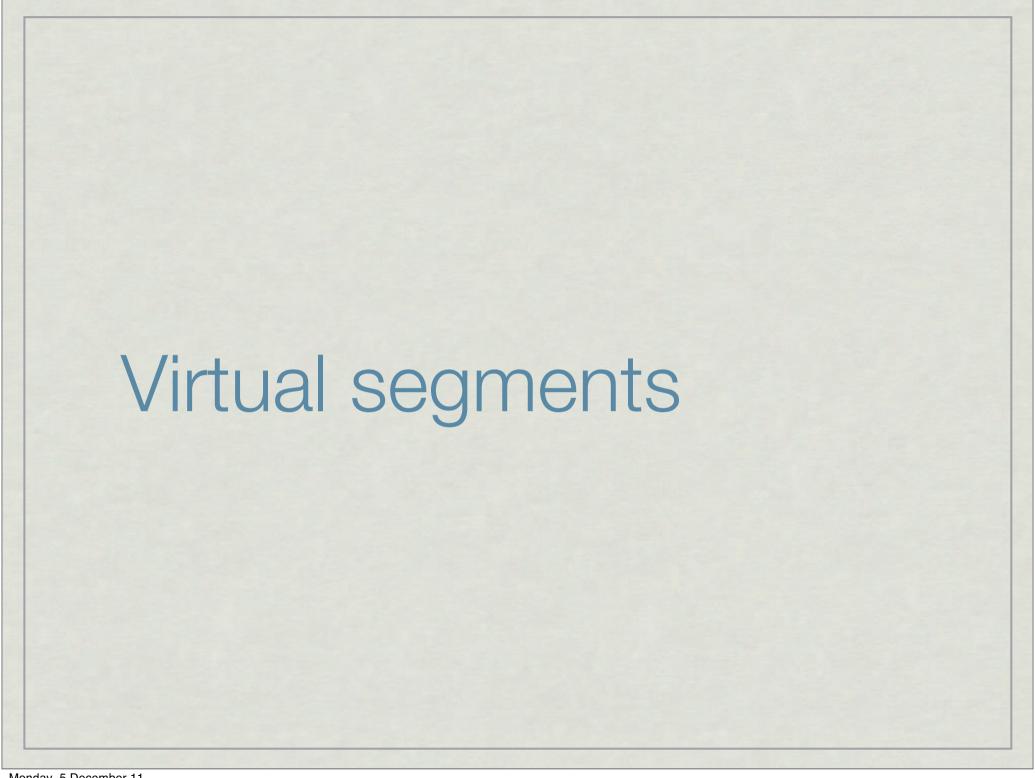
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xs = Array (Array Int)
xs = [[1 2 3] [8 7] [0] [9 3 9 1]]
```

```
seg lens: [ 3 2 1 4 ]
```

seg starts: [0 3 5 6]

flat data: 1 2 3 8 7 0 9 3 9 3

```
data Array (Array a) = Nested Segd (Array a)
data Segd = Segd (Array Int) (Array Int)
xs = Array (Array (Array Int))
xs = [[[1 2 3][8 7]][][[0][9 3 9 1]]]
seg lens: [ 3 2 1 4 ] seg lens: [ 2 0 2 ]
seg starts: [ 0 3 5 6 ] seg starts: [ 0 5 5 ]
flat data: 1 2 3 8 7 0 9 3 9 3
```



Basic idea

* Don't copy data, keep track of repetition counts

```
replicateP 80000 [:0..89999:]
= [:[:0..89999:] [:0..89999:] ...:]
```

```
rep count: 80000
```

seg lens: [: 90000 :]

seg starts: [: 0 :]

flat data: 1 2 ··· 89999

Lifted replicate

```
replicateP^ :: [:Int:] -> [:a:] -> [:[:a:]:]
    replicateP<sup>^</sup> [:2 3 1:] [:xs ys zs:]
        = [:xs xs ys ys ys zs:]
virt seg ids: [:0 0 1 1 1 2:]
phys seg lens: [:5 3 8:]
                                           used physical
phys seg starts: [:0 5 8:]
                                             segments
flat data: | x1 | x2 | x3 | x4 | x5 | y1 | y2 | y3 | z1 | z2 | z3 | z4 | z5 | z6 | z7 | z8
              0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
```

Consumers: Packing

```
virt seg ids: [:0 1 2 3 4:]
phys seg lens: [:3 2 5 1 5:]
phys seg starts: [:0 3 5 10 11:]
```

```
flat data: a1 a2 a3 b1 b2 c1 c2 c3 c4 c5 d1 e1 e2 e3 e4 e5

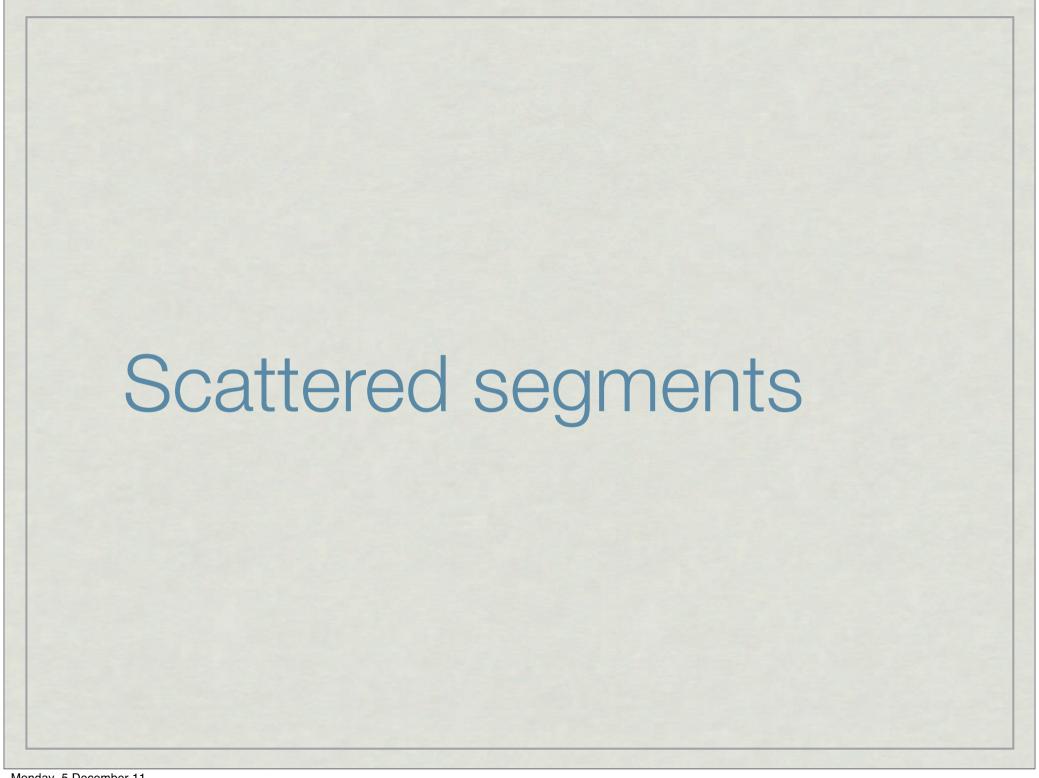
0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
```

Consumers: Packing

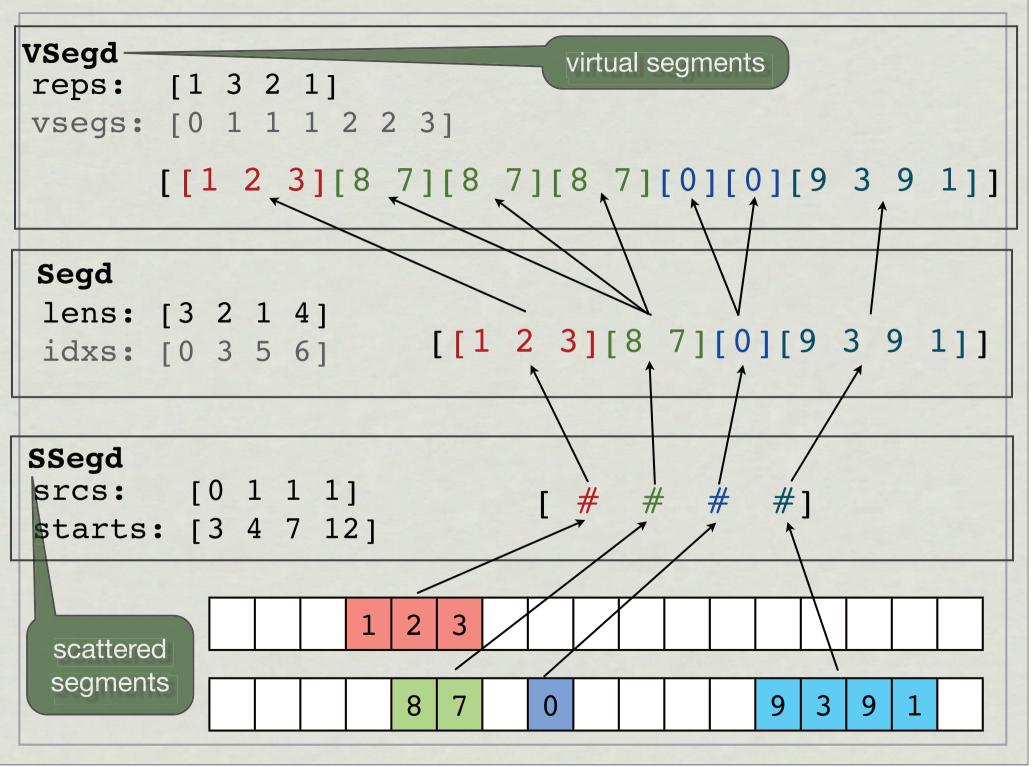
```
pack :: [:Bool:] -> [:a:] -> [:a:]
 pack [:T F T T F:] [:as bs cs ds es:]
   = [:as cs ds:]
                  [:T T T:]
virt seg ids: [:0 2 3:]
phys seg lens: [:3 2 5 1 5:]
phys seg starts: [:0 3 5 10 11:]
flat data: a1 a2 a3 b1 b2 c1 c2 c3 c4 c5 d1 e1 e2 e3 e4 e5
           0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
```

Consumers: Packing

```
pack :: [:Bool:] -> [:a:] -> [:a:]
 pack [:T F T T F:] [:as bs cs ds es:]
    = [:as cs ds:]
                    [:T T T:]
virt seg ids: [:0 1 2:]
phys seg lens: [:3 5 1:]
phys seg starts: [:0 5 10:]
flat data: | a1 | a2 | a3 | b1 | b2 | c1 | c2 | c3 | c4 | c5 | d1 | e1 | e2 | e3 | e4 | e5
             0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15
```

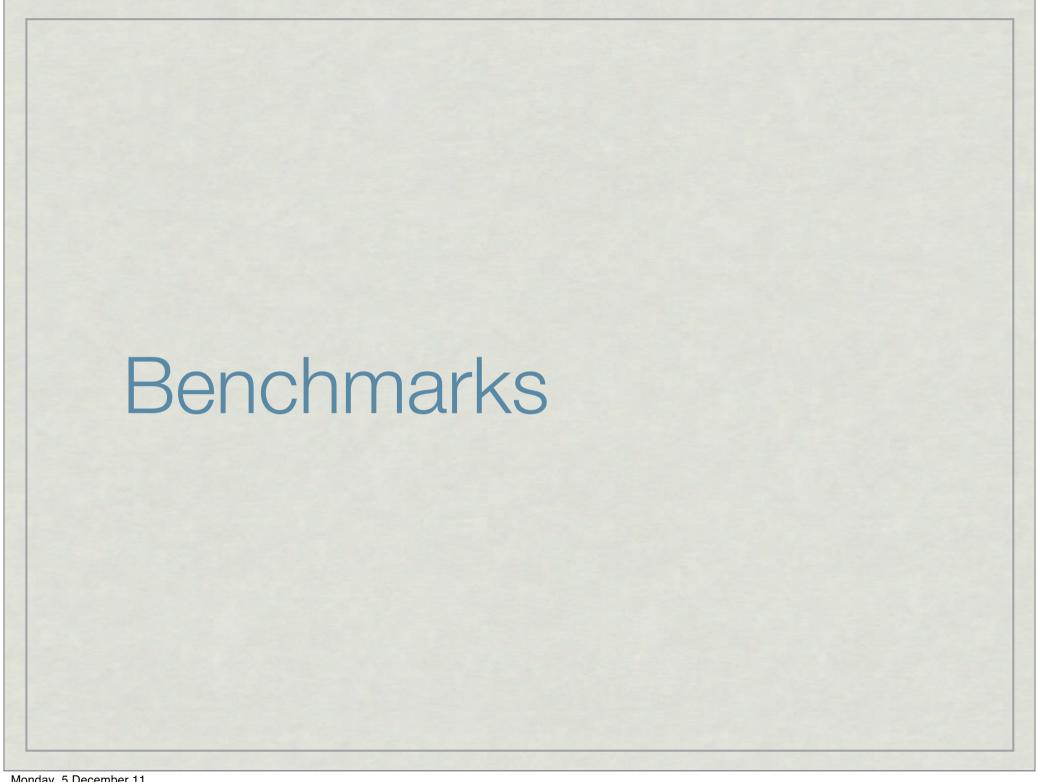


* replicate (segmented) * index & slice (segmented) ** split & combine (segmented) * append (segmented) assemble a segmented array from (two) others * back permutation



Summary

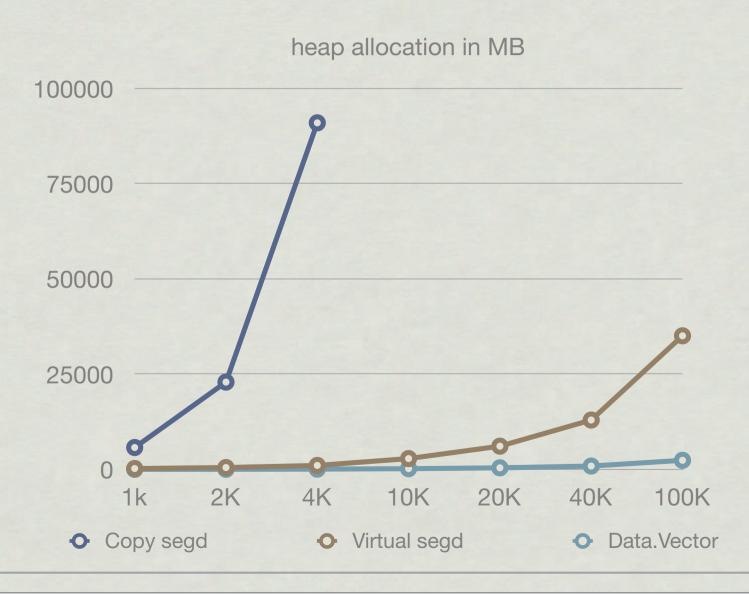
- * Virtual segments: encoding repetition
- * Sparse virtual segments: encoding packing
- * Scattered segments: encoding combinations of multiple subarrays



Implementation status

- * Implemented DPH library with scattered and virtual segment descriptors
- * Basic implementation that still misses some important optimisations
- * It runs all our test and example programs
- * Will be available with GHC 7.4.1

Barnes Hut



As Ben put it,

"we've made it to the ball park, but haven't yet stepped on the field..."

Conclusions



- * With flattening, shared data structures need special treatment
- * Delay index-space transformations; leave flattening as it is
- * More on Data Parallel Haskell:

http://haskell.org/haskellwiki/GHC/Data_Parallel_Haskell